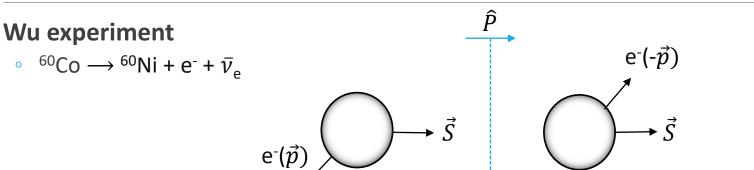


A method for searching for parity violating physics at the LHC

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$\widehat{P}(\mathbf{x}, \mathbf{y}, \mathbf{z}) \rightarrow (-\mathbf{x}, -\mathbf{y}, -\mathbf{z})$ $\widehat{P}(p_T, \eta, \phi) \rightarrow (p_T, -\eta, \phi \pm \pi)$



 \vec{B}

- Close to 0 Kelvin
- Spins of ⁶⁰Co aligned by a B field
- Observed e^- emitted preferentially in hemisphere opposite to applied \vec{B} field

- The function \vec{B} . \vec{p} is parity-odd, since \vec{B} is an axial vector
 - Expected value of \vec{B} . \vec{p} = 0 in absence of parity violation

Why parity violation?

• Asymmetry in \vec{B} . $\vec{p} \Rightarrow$ parity violated

We know the Standard model violates parity in the weak interaction

 \vec{R}

- Some objects are produced more frequently than their mirror images
- Is there parity violating new physics at the energy scales probed by the LHC?

Searching for parity violation at the LHC

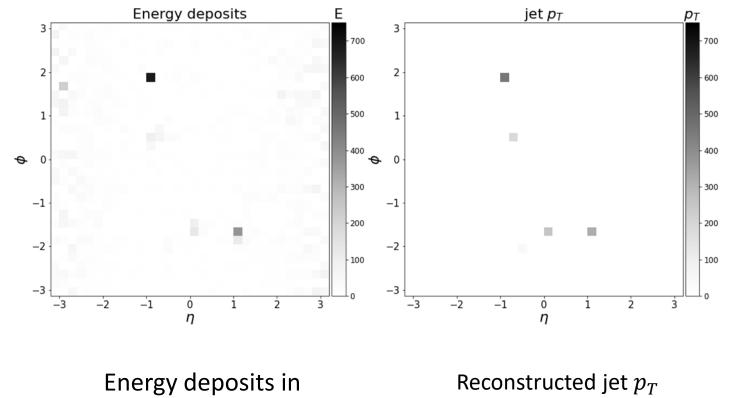
calorimeter

The goal

- Develop a model independent method to search for parity violation
 - Produced by unpolarised beams
 - Detectors not sensitive to polarisation
- Looking at momentum *or* energy information as images

The solution

- Can we see an asymmetry a parity-odd measurement function in a similar way to $\vec{B} \cdot \vec{p}$?
- $f(x) = g(x) g(\hat{P}(x))$
 - $\,\circ\,\,$ For an arbitrary function g(x)
 - $x = images in (\eta, \phi) with \ge 3jets$
 - g(x) is a convolutional neural network (CNN) satisfying φ-translation symmetry *





*probability for (x1, $\widehat{P}(x_1)$) being labelled (real, fake)

Search method

Problem statement

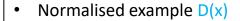
- We have a dataset drawn from distribution D(x)
- \mathbf{x} = image (energy or p_T) in our case
- o Does D(x) violate parity symmetry?

Method

- \circ Sample point x_1
- Label x₁ as *real* or *fake*
 - Real (r): point drawn from D(x)
 - Fake (f): parity transformed point
- Calculate probability of x_1 being real* as $P(real | x_1)$

Aim

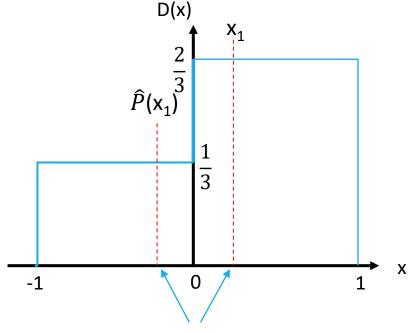
- If D(x) conserves parity, *real* or *fake* are equally likely for a point
- If D(x) violates parity, either *real* or *fake* more than 50% likely for a point



- Value on y axis indicates probability of point
- Clearly parity violating, points x > 0 are twice as likely as points x < 0

Which is the point drawn from the distribution and which is the "fake" point?

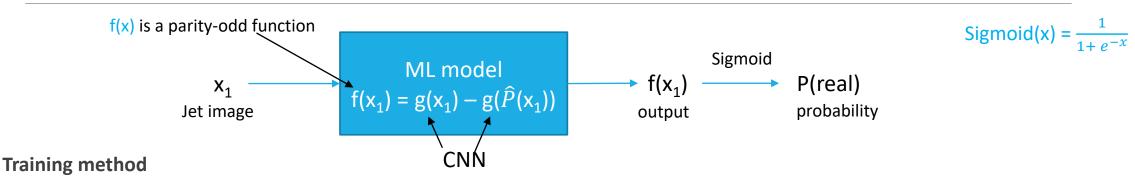
Trained classifier can assign a higher probability of x_1 being real



Machine learning setup

We can calculate [1] the probability of x_1 being drawn from $D(x)^*$

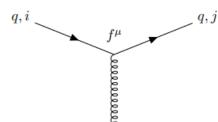
$P(real|x_1) = sigmoid\left[g(x_1) - g(\hat{P}(x_1))\right]$



- Sample points from D(x), get images in η - ϕ plane \rightarrow input to ML model
- To learn the CNN g(x): minimise Loss = $-\log P(real|x_1)$

Testing method – using trained ML model

- Sample new points from D(x)
- Calculate net output $f(x) = g(x_1) g(\hat{P}(x_1))$
- If average f(x) over dataset significantly > 0 \Rightarrow parity violation in the dataset



q, a

η is a parity-

odd variable

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Dataset used

Model used

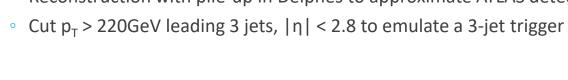
• Use a dataset that violates parity in a way that can be seen in momenta

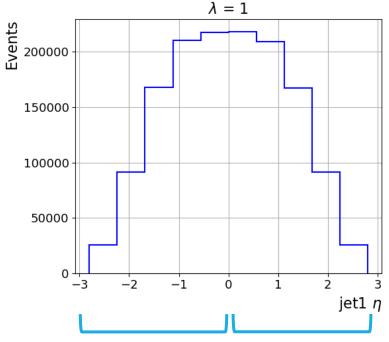
Minimal Standard-Model Extension (mSME) [1,2]

- Violates CPT and spontaneously breaks Lorentz symmetry
- Modify SM quark-gluon vertex with 4x4 coupling matrices $c_{\mu\nu}$
- Off-diagonal elements in $c_{\mu\nu}$ can cause parity violation
 - \exists terms such as $\overline{u}cu$ in \mathcal{L} , where we get components E . P which are parity odd
- Modulate effect of $c_{\mu\nu}$ by a coupling constant λ ($\lambda = 0$ is the SM)

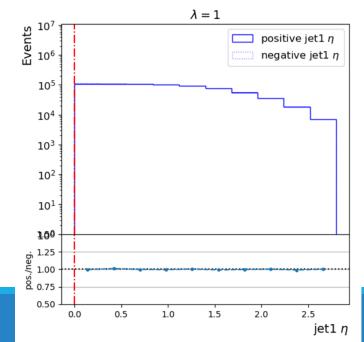
Data generation

- 3-jet mSME samples generated in Madgraph
- Showering in Pythia
- Reconstruction with pile-up in Delphes to approximate ATLAS detector





Compare positives to negatives



Training and testing

Training setup

~10M events split into three sets (train, validation, test) in (60, 20, 20) ratio

jet p_T

η

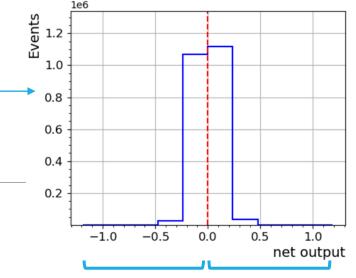
• Hyperparameters tuned on the validation set (# hidden layers, # convolution kernels, learning rate, amount of regularization, early stopping)

Results for reconstructed jet images $\lambda = 1$; see parity violation

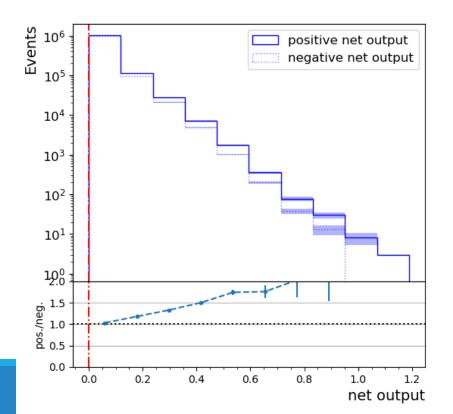
- Network output on the test set is clearly asymmetric around 0
- For a typical search, cut (e.g) |net output| > 1.0 and compare positive and negative yields

Metric, log likelihood ratio

- Comparing to a symmetric hypothesis ($P = \frac{1}{2}$ for each event)
- Log-likelihood ratio for a data point $\log P(real|x_1) \log \frac{1}{2}$
- Mean log-likelihood ratio over the dataset, Q, used as a metric.
 - Determines how much parity violation the model sees in the dataset
 - Q = 870 ± 30 ppm



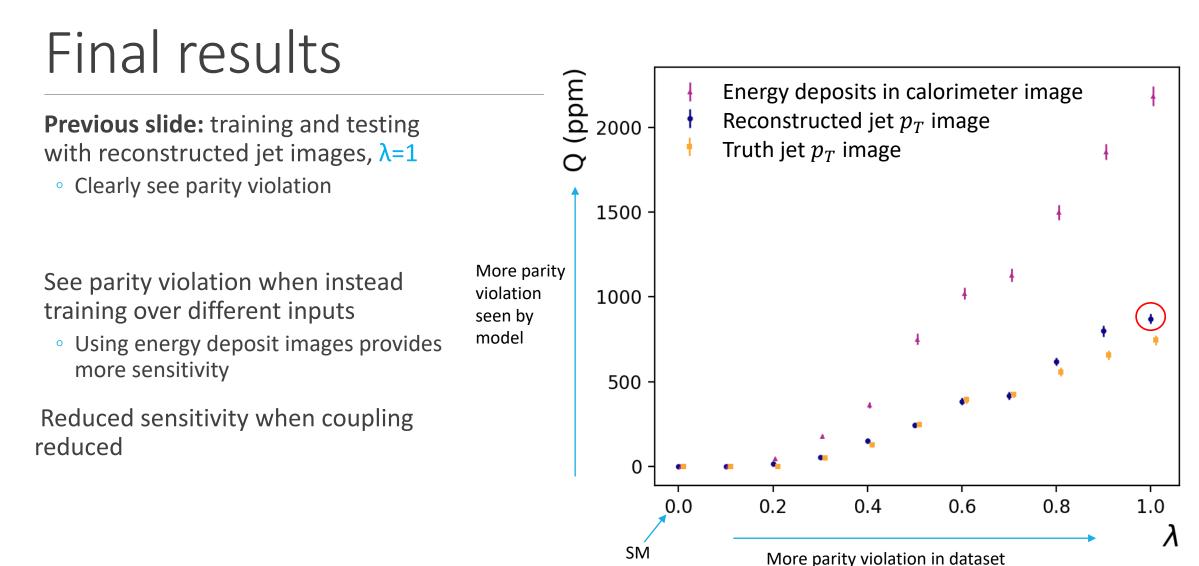
Compare positives to negatives



ML

model

Each point is a individually trained CNN



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Conclusions

Summary

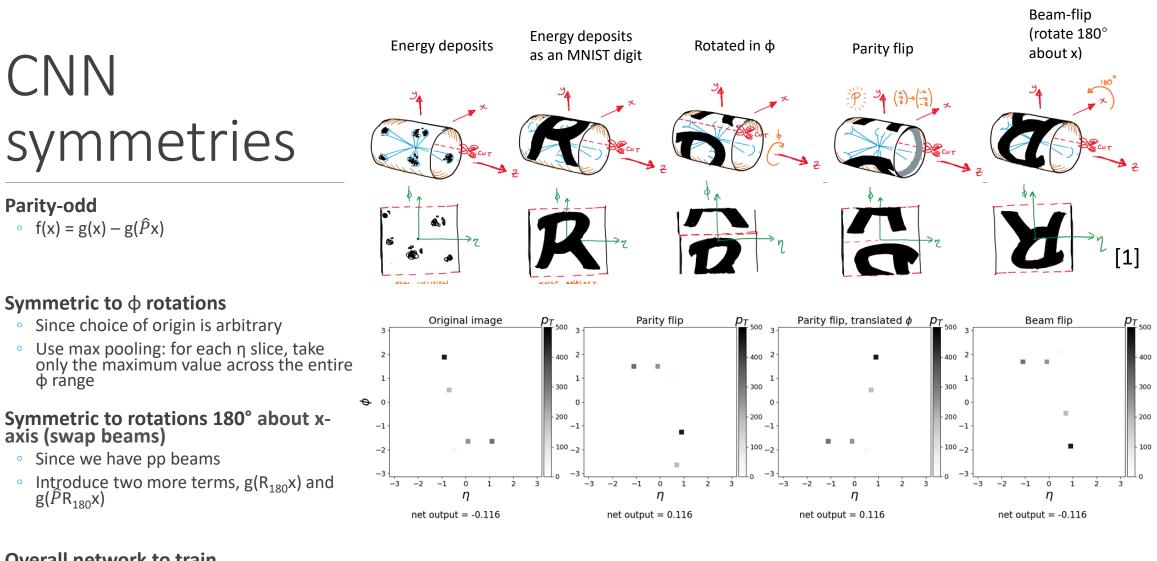
- A method has been developed for a model-independent search for parity violating physics at the LHC
- This has been developed for a 3 jet theory
 - Can be similarly performed on other physics objects e.g. electrons, muons
 - Wide range of potential final states that could be investigated

Future

- We would like to see these techniques used on real LHC data
- We plan to make the code public for sample generation and data analysis to facilitate this

Thanks for listening! Any questions?

Backup



Overall network to train • $f(x) = g(x) + g(R_{180}x) - g(\hat{P}x) - g(\hat{P}R_{180}x)$

CNN

Parity-odd

φ ránge

 $g(\hat{P}R_{180}x)$

0

Check on the network – are the desired symmetries obeyed?

$$P(\ell = (r, f)|(x_1, x_2)) = \frac{P(\ell = (r, f)|(x_1, x_2))}{P(\ell = (r, f)|(x_1, x_2)) + P(\ell = (f, r)|(x_1, x_2))}$$
$$= \frac{1}{1 + \frac{P(\ell = (f, r)|(x_1, x_2))}{P(\ell = (r, f)|(x_1, x_2))}},$$

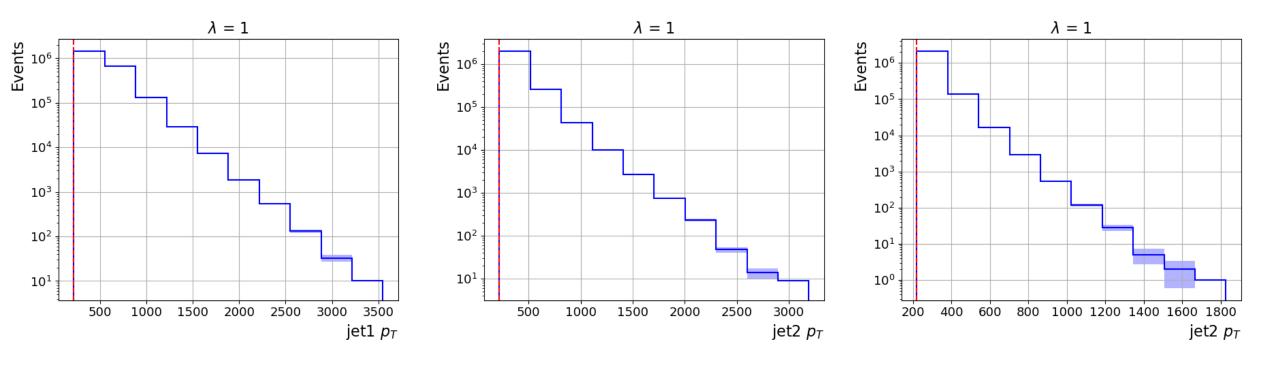
$$\mathbf{x}_2 = \widehat{P}(\mathbf{x}_1)$$

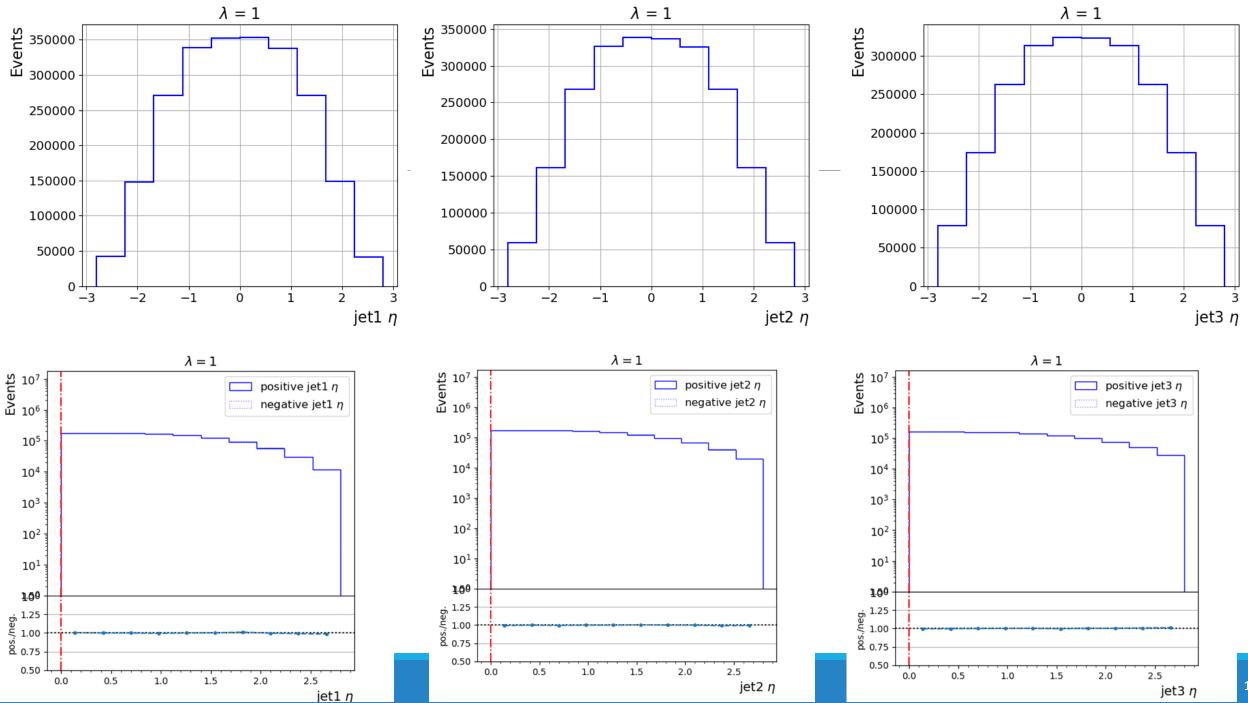
 $P(real) = P(\ell = (r,f))$

$$\begin{aligned} \frac{P(\ell = (\mathbf{f}, \mathbf{r}) | (x_1, x_2))}{P(\ell = (\mathbf{r}, \mathbf{f}) | (x_1, x_2))} &= \frac{P(\ell = (\mathbf{f}, \mathbf{r}), (x_1, x_2))P(x_1, x_2)}{P(\ell = (\mathbf{r}, \mathbf{f}), (x_1, x_2))P(x_1, x_2)} \\ &= \frac{P(x_1 = \mathbf{f} = \hat{P}x_2, x_2 = \mathbf{r})}{P(x_1 = \mathbf{r}, x_2 = \mathbf{f} = \hat{P}x_1)} \\ &= \frac{P(x_1 = \mathbf{f} | x_2 = \mathbf{r})P(x_2 = \mathbf{r})}{P(x_2 = \mathbf{f} | x_1 = \mathbf{r})P(x_1 = \mathbf{r})} \\ &= \frac{\tau(x_2, x_1)D(x_2)dx}{\tau(x_1, x_2)D(x_1)dx} \\ &= \frac{D(x_2)}{D(x_1)} \end{aligned}$$

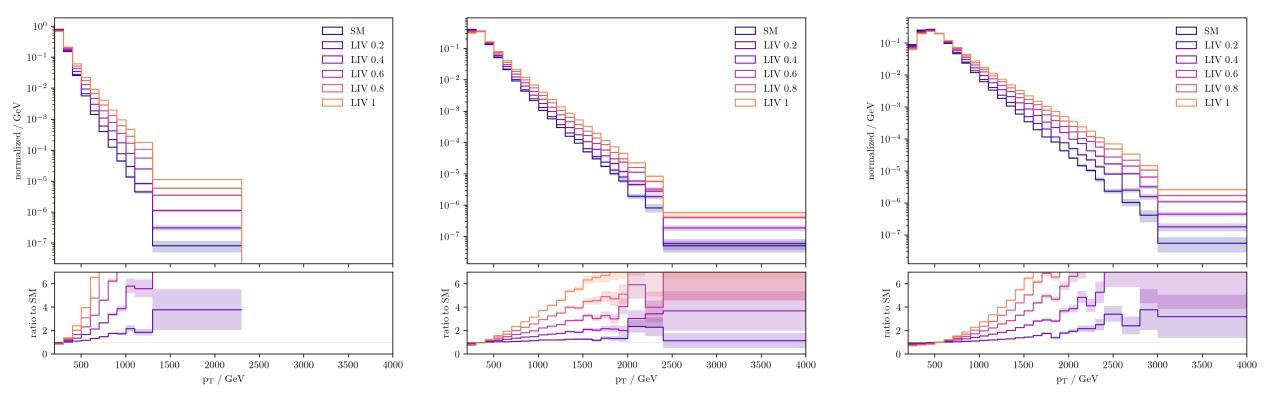
$$\log \frac{P(\ell = (\mathbf{f}, \mathbf{r}) | (x_1, x_2))}{P(\ell = (\mathbf{r}, \mathbf{f}) | (x_1, x_2))} = \log D(x_2) - \log D(x_1) = g(x_2) - g(x_1)$$

LIV plots





mSME multiple couplings



mSME multiple couplings

