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CMS HLT GPU implementation

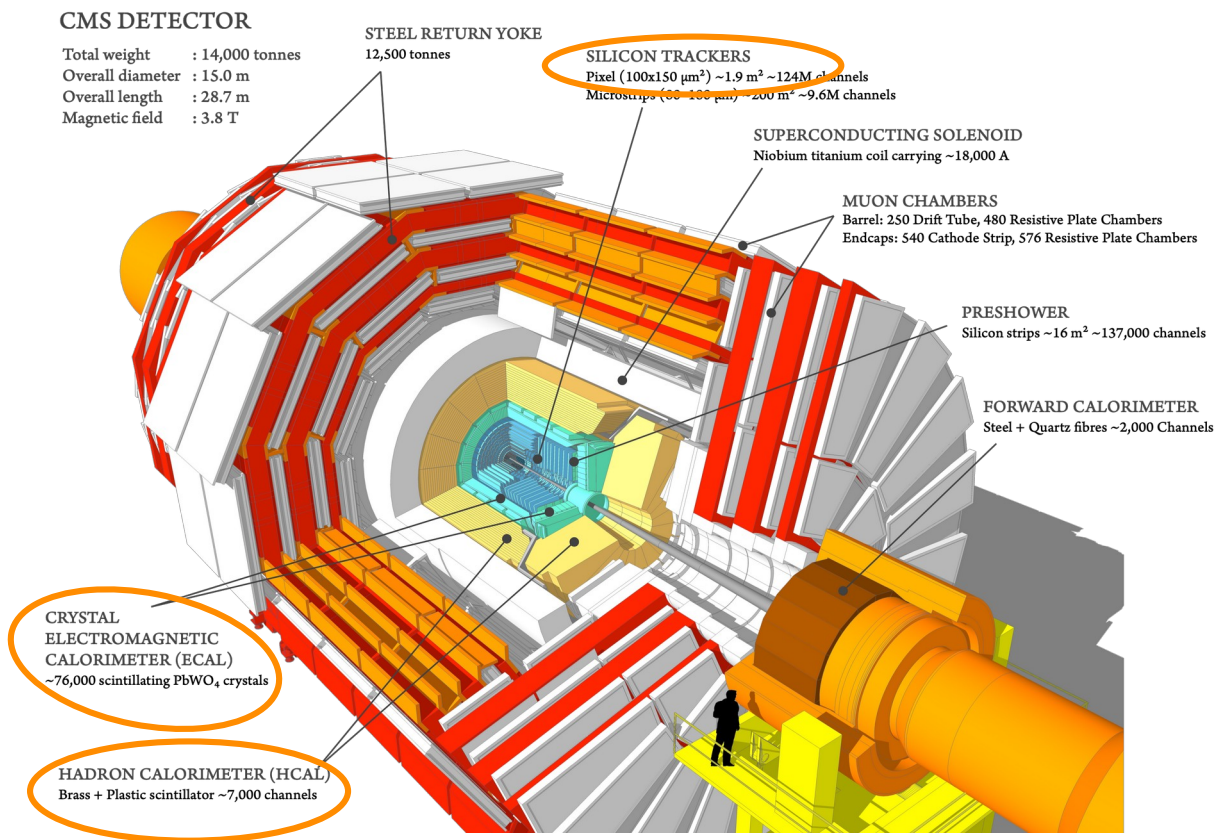
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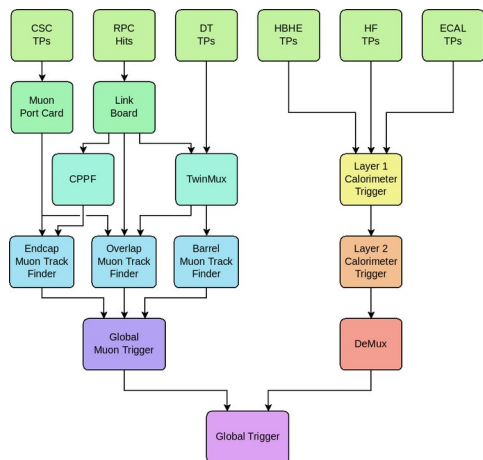
Beginner's GPU programming course for UK particle physicists

3rd September 2024

- The CMS detector is one of four experiments at the CERN LHC
- Several sub-detectors use GPU code for local reconstruction



- CMS uses a two step trigger system to select interesting events for physics analysis
- **Level-1 trigger (L1)**
 - ▶ Uses information from muon system and calorimeters
 - ▶ Sees all events
 - ▶ Custom hardware boards with large FPGAs
 - ▶ Firmware performs the reconstruction and selection depending on physics analysis requirements
 - ▶ Trigger decision in $3.8 \mu\text{s}$ (fixed latency)
 - ▶ Reduces event rate from 40 MHz to $\sim 100 \text{ kHz}$
- **High Level Trigger (HLT)**
 - ▶ Uses full detector information read out after L1 accepted an event
 - ▶ Large filter farm using GPUs
 - ▶ Runs CMSSW framework for reconstruction and filtering
 - ▶ $\sim O(450 \text{ ms})$ processing time per event
 - ▶ Reduces L1 event rate to $\sim 5 \text{ KHz}$



- The High Level Trigger is part of the CMS data acquisition chain
- For L1 accepted events the full detector information is read out from the front end electronics and sent to the HLT filter farm on the surface
- HLT paths reconstruct and select events based on physics analysis requirements
 - All paths together make the HLT “menu”
- Opportunistic use of capacity not required for triggering as T2 grid site



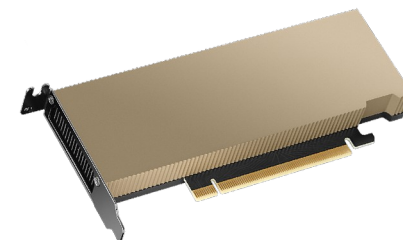
2022 configuration:

- 200 nodes, each with
 - 2 AMD EPYC 7763 “Milan” (64 cores each)
 - 2 NVIDIA Tesla T4 GPUs (2560 CUDA cores, 16 GB memory)
 - 256 GB system memory
- Total of 25,600 CPU cores and 400 GPUs

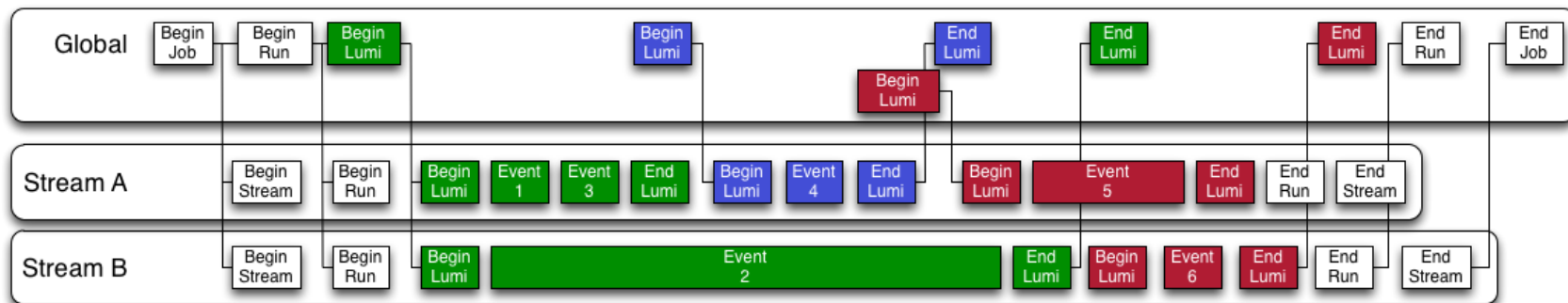


2024 upgrade:

- 18 nodes, each with
 - 2 AMD EPYC 9754 “Bergamo” (128 cores each)
 - 3 NVIDIA L4 GPUs (7680 CUDA cores, 24 GB memory)
 - 768 GB system memory
- Addition of 4608 CPU cores and 54 GPUs (+20%)

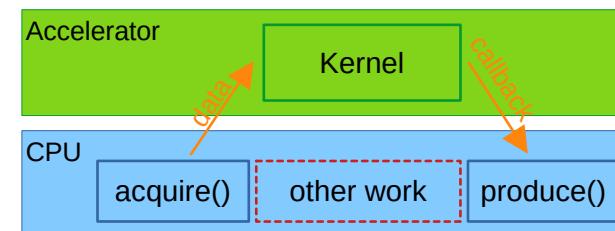


- The CMS software framework (CMSSW) is used at the HLT, for offline reconstruction, and simulation
 - Open source on [github](https://github.com) with > 1.1k contributors
- Written in C++ with one executable (cmsRun)
 - Plugin modules selected and configured by python scripts
- Multi-threaded processing
 - Concurrent events, processed in streams
 - Concurrent luminosity sections (~23 s chunks of data)
 - Concurrent runs
- Full support for asynchronous work on external accelerators

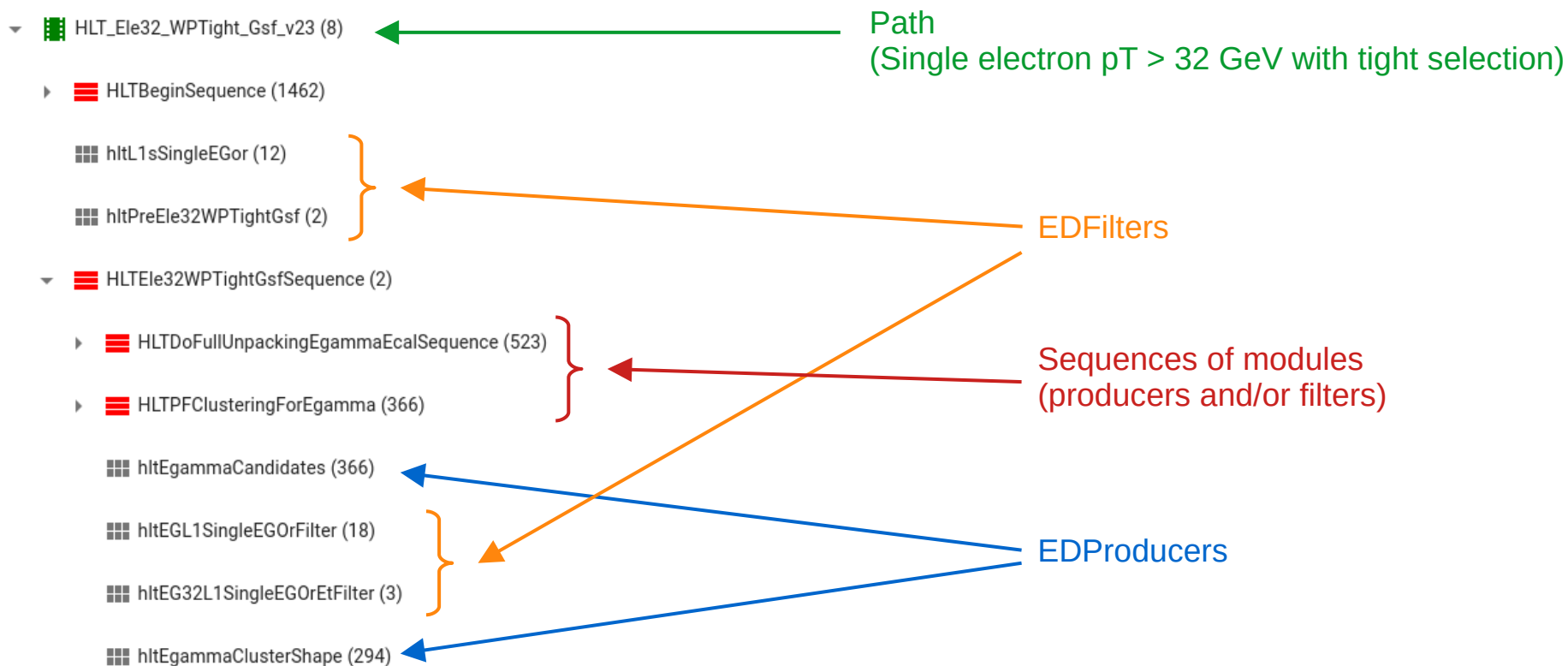


Transitions seen during event processing

- CMSSW has different module types that are loaded dynamically
- EDProducers
 - Take collections of objects as input and use them to produce derived collections
 - E.g. Take digitised samples and perform an amplitude reconstruction to output amplitude values
 - A special version exists for asynchronous work
 - acquire() function launches the asynchronous work
 - produce() function is called once the asynchronous work has finished
- EDFilters
 - Based on input collections make decisions if an event should be processed further
 - E.g. filter events with at least two muons with pT above a threshold
 - Particularly important for efficient processing of events at the HLT
- EDAnalyzers
 - Analyse event data and e.g. produce histograms
- ESProducers
 - Producing Event Setup conditions like calibrations or configurations



- HLT paths perform real time event reconstruction and selection
- One path consists of several EDProducers and EDFilters to gradually reconstruct more complex information from the raw data
- Processing of events not passing a filter is stopped to save resources



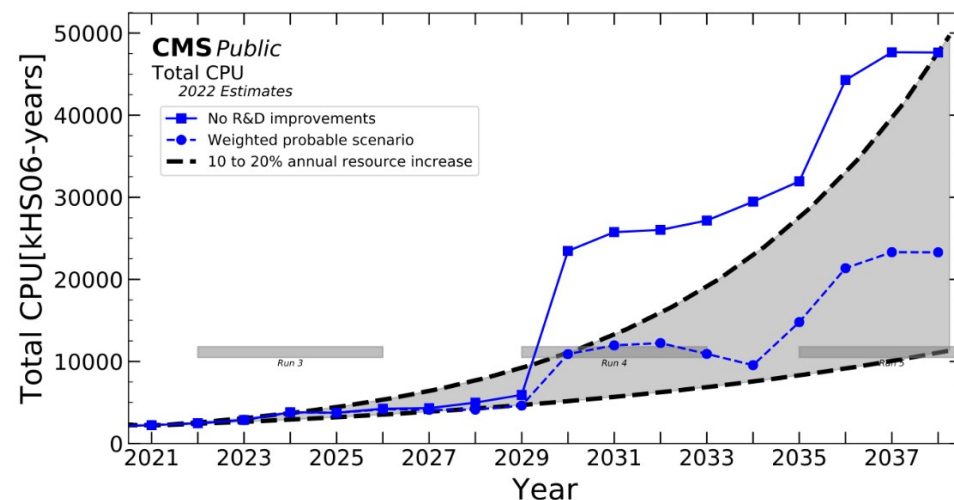
- 2016: Start of investigations to offload reconstruction to GPUs
- 2017: CUDA code on pixel local reconstruction
- 2018 – 2020: R&D on algorithms and data structures, memory and caching
 - CUDA algorithms for ECAL and HCAL local reconstruction
 - Automatic offloading when GPUs are available
- 2021: Integration at the HLT
- 2022: Deployment of GPU reconstruction at the HLT
- 2023: Migration to Alpaka
 - Framework support for Alpaka and new SoA format
 - Migration of existing CUDA algorithms
- 2024: Deployment of Alpaka based code for some algorithms

- **Because we can**

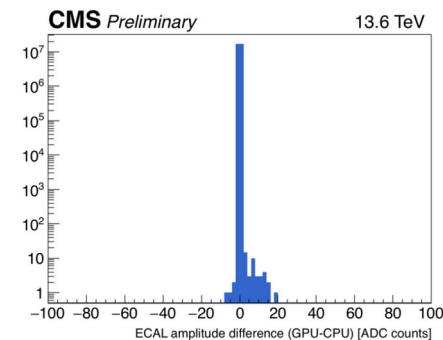
- ▶ Many tasks in event reconstruction are independent of each other
 - E.g. unpacking and reconstruction of subdetector data
 - Independent reconstruction of channels
- ▶ Events are independent and can be processed concurrently
- ▶ Framework takes care of scheduling

- **Because we have to**

- ▶ High luminosity LHC updates will bring new highly granular detectors and a 2.5 fold increase in instantaneous luminosity
- ▶ This translates to 30x increase in required computing resources for similar physics goals
- ▶ Not achievable with given budget by relying on CPU performance increase alone
- ▶ Parallelism and algorithmic improvements are needed
- ▶ Lower power consumption for same performance

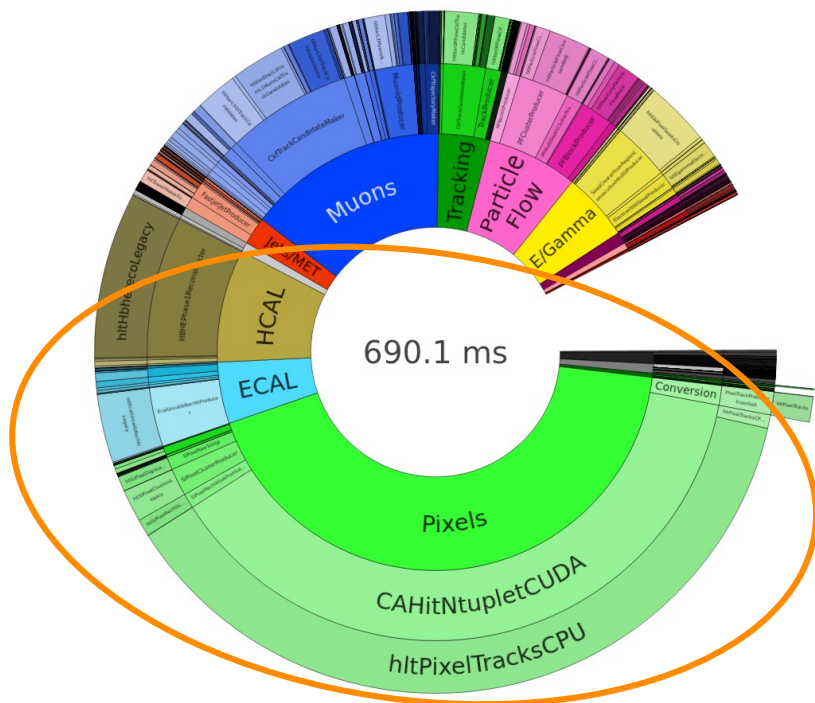


- Offloading to GPUs is fully integrated in the CMSSW framework
- Part of the reconstruction algorithms rewritten to offload to GPUs
 - Initially using CUDA for NVIDIA GPUs
 - Partially ported to Alpaka
- Deployed at the HLT since the beginning of LHC Run 3 (2022)
 - Algorithms: Pixel local reconstruction, Pixel tracking, ECAL and HCAL local reconstruction
 - More algorithms being ported
- Offloading up to 40% of runtime to GPUs
- Validation and monitoring using the CMS Data Quality Monitoring system
 - CPU vs. GPU validation of fraction of events from HLT
- Code can also be used for offline reconstruction

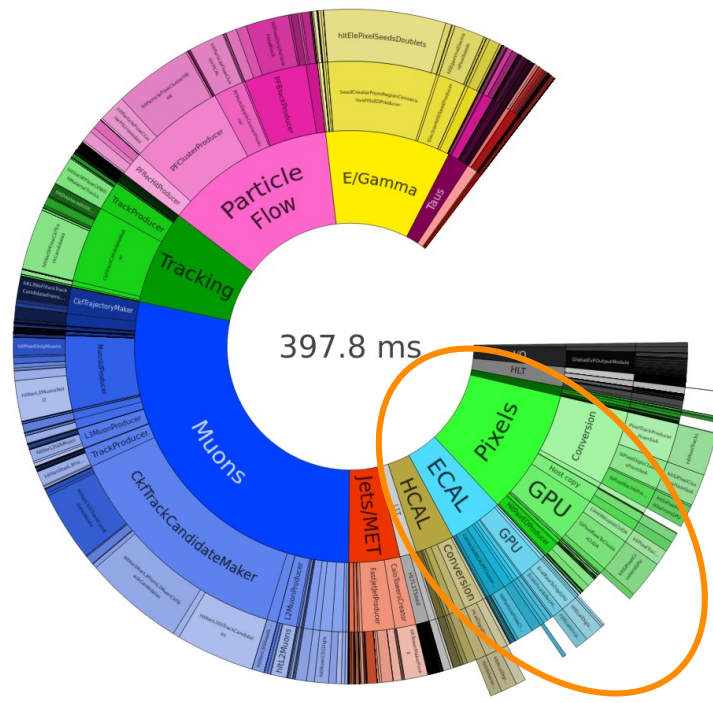


- HLT with GPU offloading (2022 numbers)
 - 40% less time per event
 - 50% better performance per W
 - 20% better performance per initial cost

https://cds.cern.ch/record/2851656/files/DP2023_004.pdf



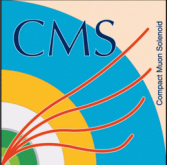
No GPU, 32 threads, 24 streams



GPU, no MPS, 32 threads, 24 streams



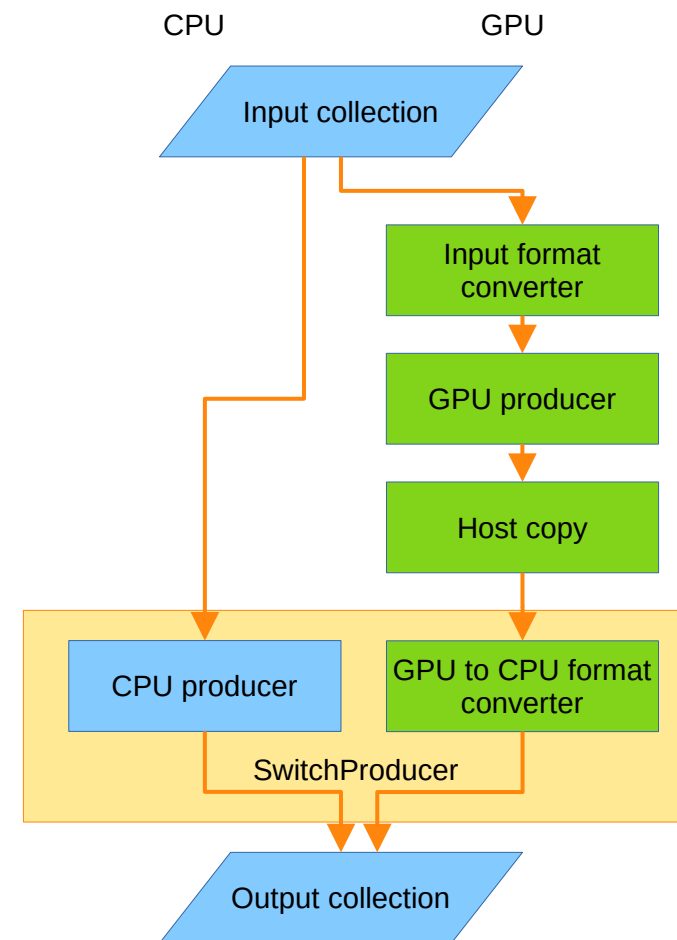
- CMS has chosen Alpaka as performance portability library
- Alpaka provides portability of code for various backends by adding an abstraction layer for the backends parallelism
- All backends of interest for CMS are supported
 - Serial (CPU)
 - NVIDIA and AMD GPUs
 - Intel GPUs and FPGAs (experimental)
- Performance close to native code
- Open source
 - Some improvements contributed already by CMS people
- Alpaka support added to CMSSW
 - Documentation
 - Examples
- Some CUDA algorithms ported to Alpaka and in production
 - More currently being ported
 - Some newly developed directly with alpaka



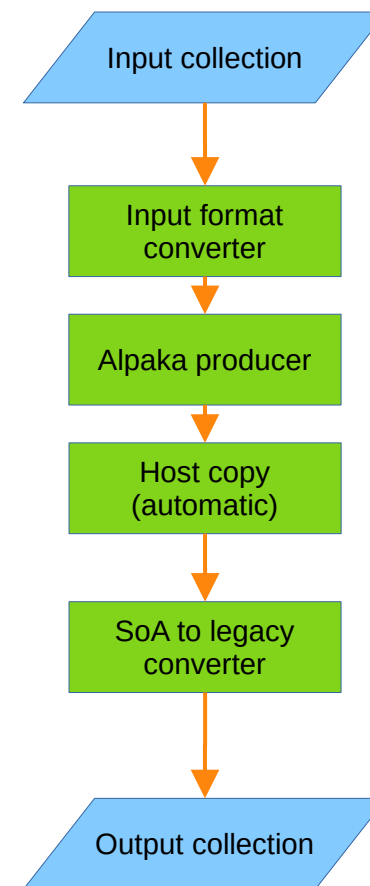
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Framework implementation details

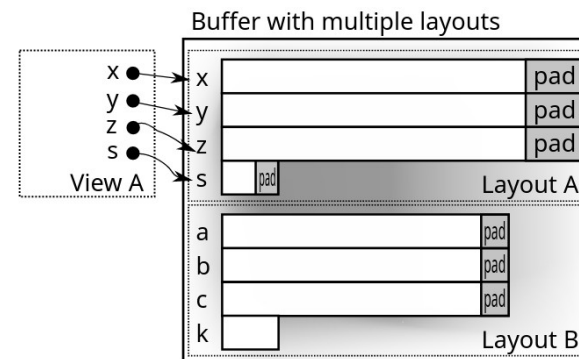
- Separate CPU and CUDA versions of the algorithms
- The framework needs to run the right module based on the availability of a GPU
- Solved by SwitchProducerCUDA module
 - A special module in the python configuration for cmsRun pointing to a CPU producer module or a GPU producer module
 - Output collection type of the two branches must be the same
- In practice the GPU branch module is a module that converts the GPU data format to the legacy CPU format
 - The actual GPU algorithm module is automatically scheduled by the framework to run before the conversion module



- Alpaka eliminates the need for a SwitchProducer module
 - Backends are chosen automatically depending on availability
- Still requires a conversion module to legacy data formats for downstream CPU modules
- The framework automatically takes care of the host copy if needed
 - In case a CPU module requires a data product produced on an accelerator
- Automatic device copies are provided for conditions consumed on a device
- Provides various functions to help with looping over elements
- The Alpaka dependent code is compiled for each backend
- Code for accelerators is placed in a special namespace whose values depend on the backend the code is compiled for

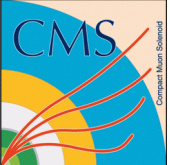


- In order to work efficiently parallel algorithms need data formatted as structures-of-arrays (SoA)
 - Minimise memory access operations
 - Legacy data formats in CMSSW are arrays-of-structures (AoS)
 - AoS “feels” more intuitive to many developers
- New generic SoA data format developed
 - Usable with CUDA and Alpaka code
 - Layout divides a buffer and views to access the data
 - Supports columns (vectors), scalars, and Eigen like matrices
- Portable collections (host and device side) wrap SoA format layout and views
 - Manages buffer allocations, interface to memory transfers, and serialisation to ROOT files
 - Access syntax close to AoS



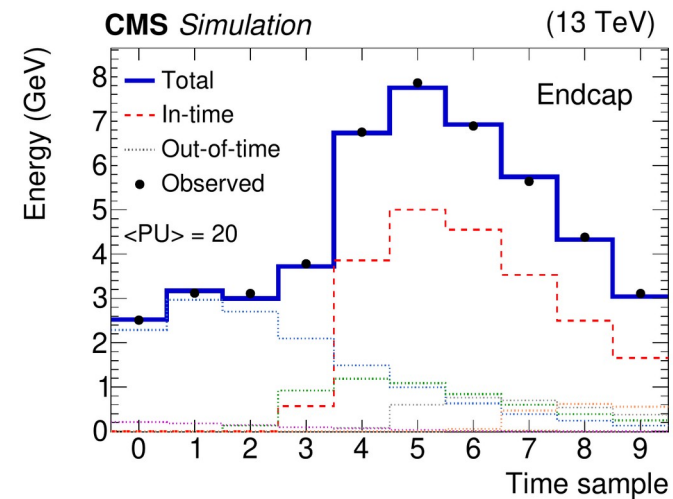
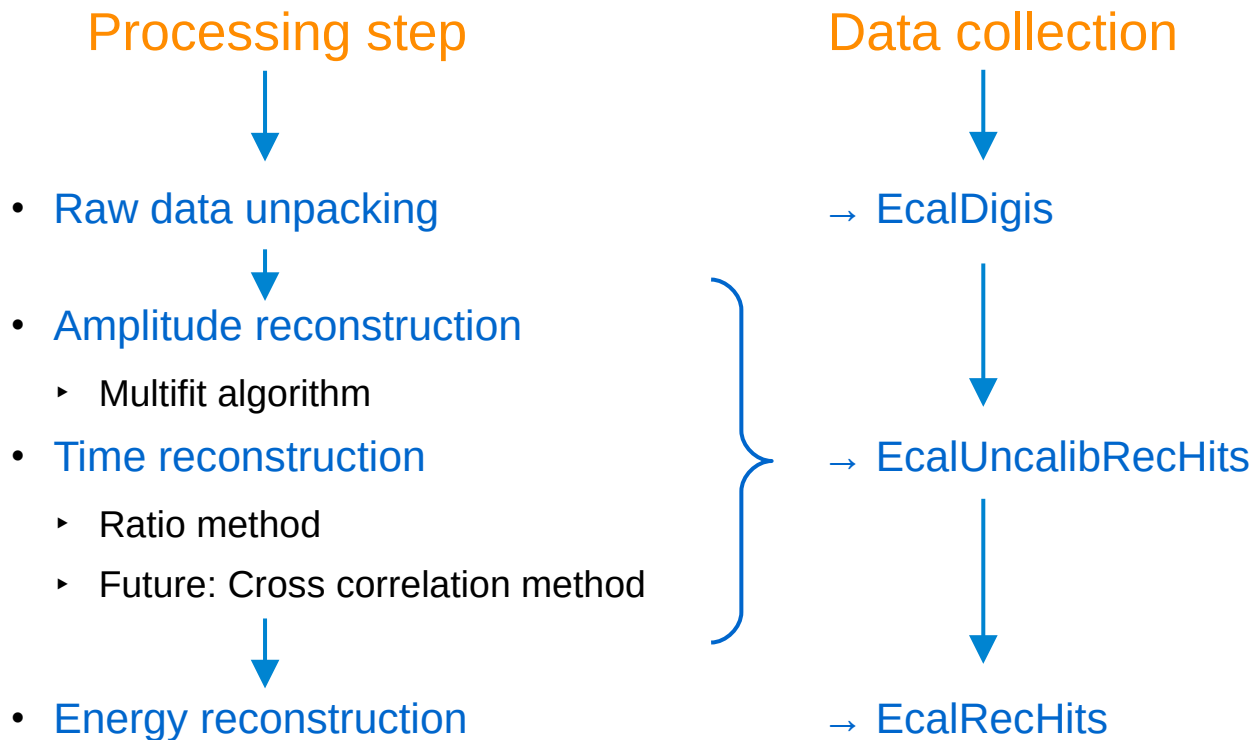
```
GENERATE_SOA_LAYOUT(TestSoALayout2,
    // columns: one value per element
    SOA_COLUMN(double, x2),
    SOA_COLUMN(double, y2),
    SOA_COLUMN(double, z2),
    SOA_COLUMN(int32_t, id2),
    // scalars: one value for the whole structure
    SOA_SCALAR(double, r2),
    // Eigen columns
    // the typedef is needed because commas confuse macros
    SOA_EIGEN_COLUMN(Matrix, m2))
```

```
using TestSoA2 = TestSoALayout2<>;
```

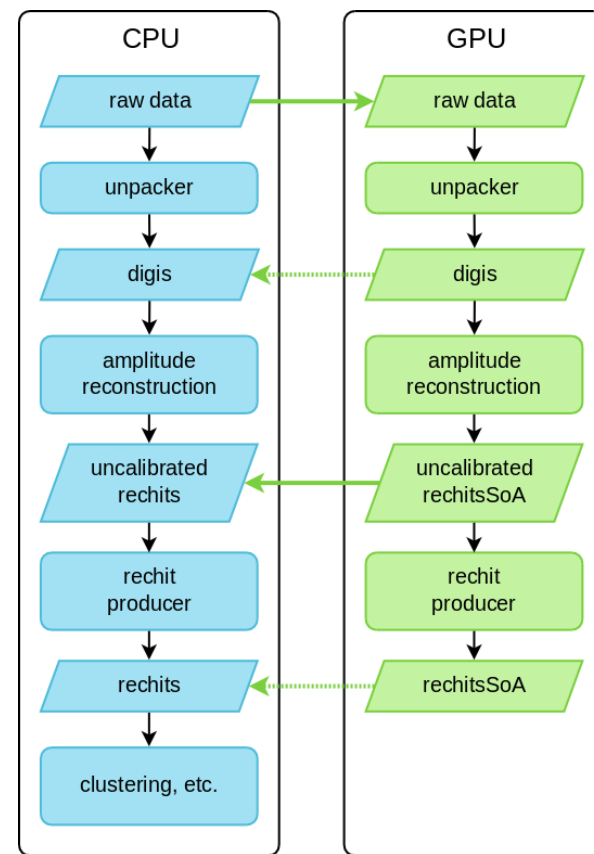
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ECAL local reconstruction



ECAL multifit reconstruction

- Running at the HLT during Run 3
- Mostly migrated to Alpaka from original CUDA version
- Modules
 - Unpacker for digis
 - Multifit amplitude and time reconstruction
 - Energy reconstruction
 - Not all CPU features are available in GPU version
E.g. Energy recovery
 - Not running at the HLT
 - Various conversion modules between legacy and portable data formats



ECAL reconstruction chain with GPUs

- Data formats

- EcalDigiSoA
- EcalDigiPhase2SoA (for HL-LHC upgrade)
- EcalUncalibratedRecHitSoA

- Only digi data formats differ between Run 3 and Phase 2

- Explicit size scalar part of data format

- Because of zero suppression in raw data the number of digis is only known at runtime

- Conditions data formats (conditions for all channels also stored as SoA)

- EcalElectronicsMappingSoA
- EcalMultifitConditionsSoA
- EcalMultifitParametersSoA

```
GENERATE_SOA_LAYOUT(EcalUncalibratedRecHitSoALayout,
    SOA_COLUMN(uint32_t, id),
    SOA_SCALAR(uint32_t, size),
    SOA_COLUMN(float, amplitude),
    SOA_COLUMN(float, amplitudeError),
    SOA_COLUMN(float, pedestal),
    SOA_COLUMN(float, jitter),
    SOA_COLUMN(float, jitterError),
    SOA_COLUMN(float, chi2),
    SOA_COLUMN(float, 00Tchi2),
    SOA_COLUMN(uint32_t, flags),
    SOA_COLUMN(uint32_t, aux),
    SOA_COLUMN(Ecal00tAmpArray, outOfTimeAmplitudes))
```

```
using EcalUncalibratedRecHitSoA = EcalUncalibratedRecHitSoALayout<>;
    ECALUncalibratedRecHitSoA
```

- In the current implementation all kernels use the same queue
- [Unpacking kernel](#)
 - 1D kernel with 32 channels per block
- [Amplitude kernels](#)
 - 1D and 2D kernels prepare the input data for the minimisation
 - Minimisation kernel uses the same core function than HCAL algorithm
- [Timing kernels](#)
 - 6 separate kernels for initialisation, correction for the pre-amplifier slew rate, calculation of the null hypothesis, ratio method calculation, chi2 and amplitude, and final time corrections

- Significant improvement in reconstruction time (~50% faster)
- Initial memory consumption issues mitigated
 - Optimised unpacker memory requirements
- Unpacking of corrupted raw data can lead to problems
 - Not as many sanity checks as in CPU unpacker initially implemented
- GPU unpacker does not unpack auxiliary collections
 - Initially not planned to use them at HLT
 - Now the features are used in dead channel recovery and particle flow clustering
 - Temporary workaround: Run CPU and GPU unpacker and use aux. collections from CPU unpacker
 - Work ongoing to upgrade unpacker to unpack aux. collections

- New generic SoA formats and portable collections simplify algorithm code enormously
- Automatic device to host copies of data and host to device copies of conditions allow to remove several dedicated framework modules
- Much of the kernel code did not need to be changed
 - Mostly changes to kernel interfaces and due to use of new portable collections
 - Core fit function could stay the same (also used by HCAL local reconstruction)
 - Some loops needed to be split in outer and inner loops order to use shared memory
 - On GPU there are multiple threads each working on one element (no inner loop was needed in CUDA version)
 - On CPU one thread works on multiple elements and inner loops over the elements are needed, separated by synchronisations
- Migration of unpacker and amplitude and time reconstruction modules still took more than a year
 - ~5k lines of code spread over ~100 files
 - Adapt to framework changes while migrating
 - Due to the Alpaka design the compilation errors can be very hard to understand which makes debugging slow
- Reconstruction time practically unchanged from CUDA version
- Improved CPU vs. GPU agreement
 - Yes, it is the same code but compiled differently and small discrepancies can still exist

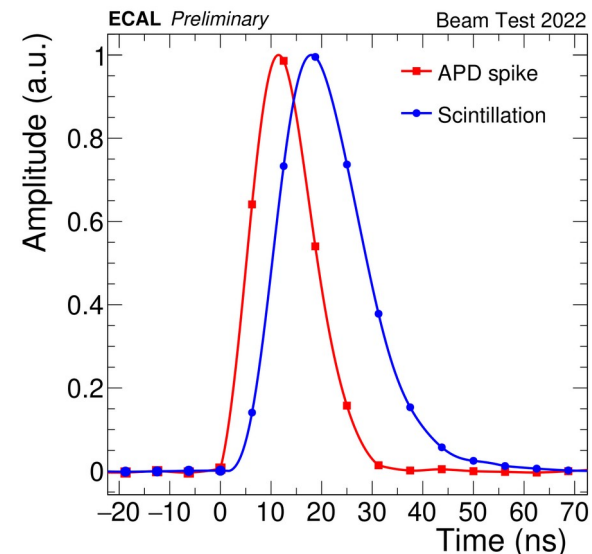
▶ Differences wrt. Run 3 reconstruction

- No ECAL endcaps
- Shorter pulses
- 16 samples per digi instead of 10
- 160 MHz sampling frequency instead of 40 MHz
-

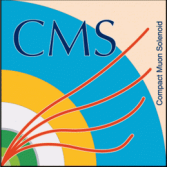
▶ Similarities wrt. Run 3 reconstruction

- ECAL barrel remains
- Same or similar data formats
- Same or similar reconstruction modules
 - Likely to use multfit algorithm for amplitude reconstruction
 - May reconstruct fewer Out-of-time PU pulses since pulses are shorter

- ▶ A weights based amplitude and time reconstruction was developed as baseline
- ▶ CUDA version of the weights algorithm developed by Southampton master student
- ▶ Alpaka migration by a second master student almost finished



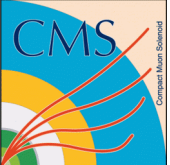
ECAL HL-LHC upgrade pulses



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Ongoing and future developments

- Work ongoing to migrate more modules to Alpaka
 - E.g. ECAL energy reconstruction
- Currently testing with non-NVIDIA GPUs (AMD)
- Add missing links to chain algorithms together on device
 - Avoid expensive copies of data back to host memory
- New developments for accelerators
 - Particle Flow clustering, Strip unpacking and clustering, Primary vertex reconstruction, Electron seeding algorithm
- Use portable code also for offline reconstruction
- Further in the future: remove legacy code



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Questions?